3D Frame Library Features

	BASIC	PROFESSIONAL	ADVANCED		
Model creation features					
Object based entities of Nodes, Elements, Diaphragms, Materials, Cross sections, Analysis options, Loads and all given parameters	\checkmark	✓	✓		
Definition of local nodal system that can be different from the global one	\checkmark	\checkmark	\checkmark		
Skew supports at user defined coordinate system	\checkmark	>	\checkmark		
Spring supports	\checkmark	\checkmark	\checkmark		
Additional nodal and element masses consideration		\checkmark	\checkmark		
Model mass can be defined using a load combination, e.g. "DEAD+0.5LIVE"		\checkmark	\checkmark		
Automatic creation of optimized Analysis model based on the given geometry	\checkmark	\checkmark	\checkmark		
Automatic subdivision of given elements at points determined by the library to ensure maximum accuracy and optimized solution time	✓	V	✓		
Support of any cross section by providing its inertia features	\checkmark	\checkmark	\checkmark		
Floor diaphragm support		\checkmark	\checkmark		
Floor diaphragm can be defined by specifying their edges in plan view and their elevation level. The library automatically applies the proper constraints to the corresponding elements/nodes.		¥	✓		
Unlimited count of load cases and combinations	\checkmark	\checkmark	\checkmark		
Load cases can be of the following types DEAD, LIVE, SUPERDEAD, SNOW, WIND, QUAKE, CRANE, OTHER for more inspectional data handling	✓	¥	V		
Concentrated nodal loads (forces, moments)	\checkmark	\checkmark	\checkmark		
Displacements/Rotations loads on nodes	\checkmark	\checkmark	\checkmark		
Unlimited number of point loads on elements	\checkmark	\checkmark	\checkmark		
Unlimited number of constant, linear, triangular, trapezoidal loads on any part of frame elements	✓	¥	¥		
Element loads can be defined with respect to their absolute or relative distance from the starting node of the element	✓	\checkmark	V		
Element loads can be applied in global, global projective or their local coordinate system	\checkmark	\checkmark	\checkmark		
Temperature loads (uniform temperature change and gradient temperature loads)	\checkmark	\checkmark	\checkmark		
Diaphragm loads		\checkmark	\checkmark		
Load cases can be combined by many combination types (Additive, Envelope, ABS, SRSS)	\checkmark	\checkmark	\checkmark		
Use of full or partial rigid dof releases	\checkmark	\checkmark	\checkmark		
User definition of modes number to find		\checkmark	\checkmark		
Response spectrum definition by providing Periods vs. Accelerations points		\checkmark	\checkmark		
Time History definition by providing Seconds vs. Accelerations accelogram points		\checkmark	\checkmark		
Specification of user defined ground motion direction for Response spectrum and time history analysis		V	×		

Element features						
6 dof node element	\checkmark	\checkmark	\checkmark			
Optimized 12 dof frame element	~	~	~			
Optimized non-linear 12 dof cable element			\checkmark			
Optimized 20 dof shell element			$\overline{\mathbf{v}}$			
Rigid offset consideration	\checkmark	\	~			
Rigid horizontal diaphragm support	-	· 🗸	~			
Timoshenko's beam theory supported			$\overline{\mathbf{v}}$			
Lumped or distributed mass model		· /	~			
Handling of any kind of dof releases	\checkmark	· _	·			
Analysis features						
Effective memory handling	\checkmark	\checkmark	\checkmark			
Optimized techniques to solve large-scale problems in minimum solution time	·	·	·			
Use of optimized sparse matrices	·	· /	~			
Automatic creation of stiffness and mass matrices so that minimum solution time is ensured		·	·			
Support of Cholesky method to efficiently solve large scale models	\checkmark	>	\checkmark			
Linear static analysis	v	v	\checkmark			
Shear deformation effects		V	V			
Elements on winkler springs considering shear deformation effects		v	\checkmark			
Modal analysis using accelerated Jacobi algorithm		v	\checkmark			
User defined modal damping ratio		v	\checkmark			
Modal superposition according to SRSS or CQC rules		·	\checkmark			
Consideration of diagonal or compact mass matrix		V	V			
Linear Response Spectrum Analysis		V	V			
Linear Time History Analysis		V	V			
Optimized non-linear solver for geometric non linearities			v			
Different update modes for non-linear analysis (after each iteration, after each load step or constant stiffness method)			v			
User defined of load steps/iterations number and convergence tolerance			\checkmark			
Results reporting features						
All results are reported per load case or load combination	\checkmark	\checkmark	\checkmark			
Deformed configuration reporting	\checkmark	\checkmark	\checkmark			
Nodal reactions reporting	\checkmark	\checkmark	\checkmark			
Internal element stresses, forces and displacements (deflections and rotations) reporting						
taking into account possible shear deformation effects (if so specified)	×	Y	Y			
Reporting of soil spring reactions		\checkmark	\checkmark			
Reporting of calculated dynamic modes		\checkmark	\checkmark			
Reporting of Periods, Eigenvalues, directional effective masses per each dynamic mode		\checkmark	\checkmark			
Calculation of Total effective mass per direction		\checkmark	\checkmark			
Time history analysis results are reported per time step		\checkmark	\checkmark			
Geometric non-linear analysis results can be reported per time step or at the final stage for lower memory usage			✓			
Reporting of floor diaphragm displacements		\checkmark	\checkmark			